Agilent Technologies

Interactive Controls and Displays

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Acknowledgments

Contents

Chapter 1: Interactive Controls and Displays

Introduction

The Interactive Controls and Displays library provides components that can interactively control the simulation and display simulation data in various forms.

Most components in this library are used to display simulation data in various forms such as bar graphs (TkBarGraph, TkHistogram, TkMeter, LMS_TkPlot, and LMS_CxTkPlot), signal level versus sample number plots (TkPlot), X signal level versus Y signal level plots (TkXYPlot), eye diagrams (TkEye), constellation plots (TkConstellation), or just numbers (TkIQrms, TkPower, TkShowValues, TkText, TkShowBooleans).

TkButtons and TkSlider allow the user to interactively change the signal level at the nodes where they are connected.

Other components provide other forms of interactively controlling the simulation such as running any Tcl script (TclScript) or breaking the simulation when a certain condition is satisfied (TkBreakPt).

Most components in this library are sinks (components with no output ports), which means that they only consume data (they do not produce data). Like the non-interactive sinks, these components will keep the simulation running as long as they need to consume data. The difference between the interactive and non-interactive sinks is that the non-interactive sinks control the amount of data they consume through parameters (typically called Start and Stop) that the user must set before the simulation starts, whereas the interactive sinks will keep consuming data until the user interactively terminates the simulation. This is further explained next.

When a design that contains components from the interactive controls and displays library is simulated, a control panel window will pop up (Figure 1-1). The control panel has two buttons: *Pause* and *Quit* (depending on what components from this library are used in the design, the control panel may display additional buttons, sliders, or text labels followed by numeric values that update as the simulation runs). Pressing *Pause* will pause the simulation and relabel the *Pause* button as *Continue*. Pressing *Continue* will resume the simulation. Pressing *Quit* will stop the simulation.

If the simulated design has non-interactive sink components and the *Quit* button is pressed before they have collected the data they need, the window shown in

Figure 1-2 will pop up warning the user that the data collection is not complete. The user has the option to resume the simulation by pressing *Continue* or terminate by pressing *Quit*.

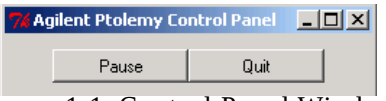


Figure 1-1. Control Panel Window

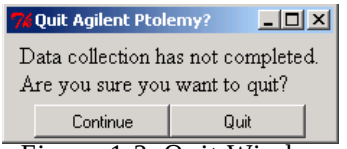


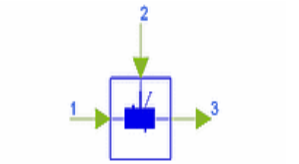
Figure 1-2. Quit Window

Interactive controls and displays components will not work in sweep simulations; they are automatically deactivated before simulation starts. Because most interactive controls and displays components do not have output ports, deactivating them does not affect the remainder of the simulation. The components that have outputs behave as explained here.

- TkSlider: the value at the output port is constant and equal to the value of the Value parameter; no slider is created in the control panel that allows interactively changing the output value.
- TkButtons: the value at the output ports is 0; no buttons are created in the control panel that allow interactively changing the output value.
- LMS_TkPlot, LMS_CxTkPlot: In the non-sweep mode these components will filter the input signal using a set of adaptively varying coefficients; a bar graph display is created that shows how the filter coefficients vary throughout the simulation. In the sweep mode, these components will still filter the input signal using a set of adaptively varying coefficients; the bar graph display will not come up.

For more information about using interactive controls and displays components refer to Chapter 12 “Using Interactive Controls and Displays” of the *ADS Ptolemy Simulation* manual.

LMS_CxTkPlot



Description Interactive Complex LMS Adaptive Filter
Library Interactive Controls and Displays
Class SDFLMS_CxTkPlot
Derived From LMS_Cx
C++ Code

Parameters

Name	Description	Default	Type	Range
Taps	filter tap values	(-.040609,0.0) (-.001628,0.0) (.17853,0.0) (.37665,0.0)(.37665,0.0) (.17853,0.0) (-.001628,0.0) (-.040609,0.0)	complex array	
Decimation	decimation ratio	1	int	[1, ∞)
DecimationPhase	decimation phase	0	int	[0, Decimation-1]
StepSize	adaptation step size	0.01	real	(0, ∞)
ErrorDelay	update loop delay	1	int	[1, ∞)
SaveTapsFile	filename in which to save final tap values		string	
StepSizeLow	low end of step size scale on interactive display	0.0	real	
StepSizeHigh	high end of step size scale on interactive display	0.1	real	
FullScale	full scale on tap display	1.0	real	
Geometry	location and size of window	+500+000	string	
Width	bar chart display width, in centimeters	10.0	real	
Height	bar chart display height, in centimeters	5.0	real	

Name	Description	Default	Type	Range
Identifier	run-time display identifier	LMS_Cx filter taps: Real (red) & Imag (blue)	string	
UpdateInterval	number of invocations between display updates	10	int	

Pin Inputs

Pin	Name	Description	Signal Type
1	signalIn		complex
2	error		complex

Pin Outputs

Pin	Name	Description	Signal Type
3	signalOut		complex

Notes/Equations

1. LMS_CxTkPlot implements an adaptive filter using the least-mean square algorithm.

   The size of the LMS filter is determined by the number of coefficients in the Taps parameter; the default gives an 8th-order, linear phase lowpass filter. LMS supports decimation, but not interpolation.

   The filter coefficients can be specified directly or read from a file. To load filter coefficients from a file, replace the default coefficients with the string <*filename*> (use an absolute path name for the filename to allow the filter to work as expected regardless of the directory where the simulation process actually runs).

2. When used correctly, this LMS adaptive filter will adapt to try to minimize the mean-squared error of the signal at its error input [1]. The output of the filter should be compared to (subtracted from) some reference signal to produce an error signal. That error signal should be fed back to the error input. The ErrorDelay parameter must equal the total number of delays in the path from the output of the filter back to the error input. This ensures correct alignment of the adaptation algorithm. The number of delays must be greater than 0 or the simulation will deadlock.

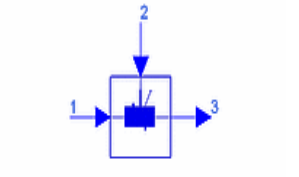
The adaptation algorithm is the well-known LMS, or stochastic-gradient algorithm.

3. If the SaveTapsFile string is non-null, a file will be created with the name given by that string, and the final tap values will be stored there after the run has completed.
4. See Also: FIR and LMS.
5. For general information regarding the control and display of simulation data, refer to the "Introduction" on page 1-1.

References

[1] S. Haykin, *Adaptive Filter Theory*, Prentice Hall: Englewood Cliffs, NJ. 1991. 2nd ed.

LMS_TkPlot



Description **Interactive LMS Adaptive Filter**
Library **Interactive Controls and Displays**
Class **SDFLMS_TkPlot**
Derived From **LMS**
C++ Code

Parameters

Name	Description	Default	Type	Range
Taps	filter tap values	-.040609 -.001628 .17853 .37665 .37665 .17853 -.001628 -.040609	real array	
Decimation	decimation ratio	1	int	[1, ∞)
DecimationPhase	decimation phase	0	int	[0, Decimation-1]
StepSize	adaptation step size	0.01	real	(0, ∞)
ErrorDelay	update loop delay	1	int	[1, ∞)
SaveTapsFile	filename in which to save final tap values		string	
StepSizeLow	low end of step size scale on interactive display	0.0	real	
StepSizeHigh	high end of step size scale on interactive display	0.1	real	
FullScale	full scale on tap display	1.0	real	
Geometry	location and size of window	+500+000	string	
Width	bar chart display width, in centimeters	10.0	real	
Height	bar chart display height, in centimeters	5.0	real	

Name	Description	Default	Type	Range
Identifier	run-time display identifier	LMS filter taps	string	
UpdateInterval	number of invocations between display updates	10	int	

Pin Inputs

Pin	Name	Description	Signal Type
1	signalIn		real
2	error		real

Pin Outputs

Pin	Name	Description	Signal Type
3	signalOut		real

Notes/Equations

1. LMS_TkPlot is an adaptive filter using the least-mean square algorithm. The initial filter coefficients are given by the Taps parameter. The default initial coefficients give an 8th-order, linear phase lowpass filter. To read initial coefficients from a file, replace the default coefficients with <*fileName*>, preferably specifying a complete path. LMS supports decimation, but not interpolation.

2. When used correctly, this LMS adaptive filter will adapt to try to minimize the mean-squared error of the signal at its error input [1]. The output of the filter should be compared to (subtracted from) some reference signal to produce an error signal. That error signal should be fed back to the error input. The ErrorDelay parameter must equal the total number of delays in the path from the output of the filter back to the error input. This ensures correct alignment of the adaptation algorithm. The number of delays must be greater than 0 or the simulation will deadlock.

   The adaptation algorithm is the well-known LMS, or stochastic-gradient, algorithm.

3. If the SaveTapsFile string is non-null, a file will be created with the name given by that string, and the final tap values will be stored there after the run has completed.

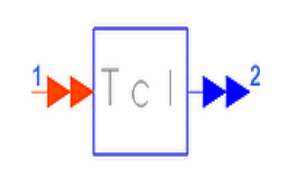
4. See Also: FIR.

5. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

References

[1] S. Haykin, *Adaptive Filter Theory*, Prentice Hall: Englewood Cliffs, NJ. 1991. 2nd ed.

TclScript



Description **Invoke Tcl Script**
Library **Interactive Controls and Displays**
Class **SDFTclScript**
C++ Code

Parameters

Name	Description	Default	Type
TclFile	file from which to read the tcl script	$HPTOLEMY/src/controls-displays/tcltk/stars/tkScript.tcl	filename

Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to feed to Tcl	multiple anytype

Pin Outputs

Pin	Name	Description	Signal Type
2	output	Any outputs obtained from Tcl	multiple real

Notes/Equations

1. TclScript reads a file containing Tcl commands. It can be used in a variety of ways, including using Tk to animate or control a simulation. A number of procedures and global variables will have been defined for use by the Tcl script by the time it is sourced. These enable the script to read the inputs to the component or set output values.The Tcl script can optionally define a procedure to be called by ADS Ptolemy for every simulation of the component.

2. Much of the complexity in using TclScript is due to the need to use unique names for each instance of TclScript. These unique names are constructed using a unique string defined by TclScript. That string is made available to the Tcl script in the form of a global Tcl variable *$starID*.

   The procedure used by the Tcl script to set output values is *setOutputs_$starID*, while the procedure used to read input values is *grabInputs_$starID*. The *setOutputs* procedure takes as many arguments as there are output ports. The *grabInputs* procedure returns a string with as many values as there are inputs, separated by spaces. The Tcl script is sourced during start-up, so it does not make sense to read inputs at that time. However, it may make sense to set output values (to initialize them).

   The Tcl script can optionally define a Tcl procedure called *goTcl_$starID*. If this procedure is defined in the script, it will be invoked every time the component simulates. It takes one argument, the *starID*, and returns no values. If the *goTcl* procedure is defined, the communication with Tcl is said to be synchronous (it is synchronized to the simulation of the component). Otherwise, it is asynchronous (the Tcl script is responsible for setting up procedures that interact with the component only when Tcl invokes them).

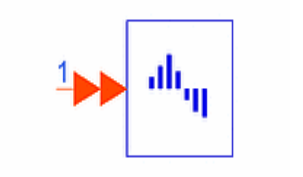
3. For asynchronous operation, typically X events are bound to Tcl/Tk commands that read or write data to the component. These Tcl commands use *grabInputs_$starID*, which returns a list containing the current value of each of the inputs, and *setOutputs_$starID*, which sets the value of the outputs. The argument list for *setOutputs_$starID* should contain a floating-point (real) value for each output of the component. Inputs can be of any type. The *print()* method of the particle is used to construct a string passed to Tcl. This mechanism is entirely asynchronous, in that the Tcl/Tk script decides when these actions should be performed on the basis of X events.

4. For synchronous operation, the Tcl procedure *goTcl_$starID* will be called by the component every time it simulates. The procedure could, for example, grab input values and calculate output values, although it can do anything the designer wishes, even ignoring the input and output values.

5. An example Tcl script is located at *adsptolemy / src /domains /sdf /tcltk /stars /tkScript.tcl* (relative to the complete ADS installation path).

6. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkBarGraph



Description **Bar Graph Display**
Library **Interactive Controls and Displays**
Class **SDFTkBarGraph**
C++ Code

Parameters

Name	Description	Default	Type
Label	Bar graph title	bar chart display	string
Top	Y-axis upper limit	1.0	real
Bottom	Y-axis lower limit	-1.0	real
NumberOfBars	Number of bars to display	16	int
BarGraphHeight	Bar graph height, in centimeters	5	real
BarGraphWidth	Bar graph width, in centimeters	10	real
Position	Bar graph window position offset from upper left corner, in pixels	+0+0	string
UpdateSize	Number of bars drawn per graph update	1	int

Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to plot	multiple anytype

Notes/Equations

1. TkBarGraph dynamically displays the value of any number of input signals in bar-graph form. The first 12 input signals will be assigned distinct colors; after that, colors are repeated. Colors can be controlled using X resources.

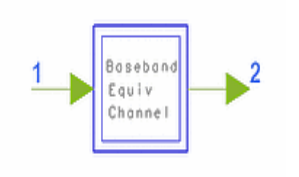
2. The UpdateSize parameter controls the number of bars drawn on the graph per graph update.

   The update occurs as described next; this description refers to one input but applies to each input if more than one signal is connected to the TkBarGraph multi-input port.

   If the total number of samples read is less than NumberOfBars, then the most recent UpdateSize samples are used to draw new bars in the graph. The first time the total number of samples read exceeds NumberOfBars, for example by N ($1 \leq N \leq$ UpdateSize), the oldest N bars are deleted before new UpdateSize bars are drawn, so that the total number of bars displayed is equal to NumberOfBars. After this point, each time UpdateSize new samples are read, the oldest UpdateSize bars are deleted from the graph and the most recent UpdateSize samples read are used to draw new bars in the graph.

3. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkBasebandEquivChannel



Description **Baseband Equivalent Channel**
Library **Interactive Controls and Displays**

Parameters

Name	Description	Default	Type
SymbolRateHz	symbol rate through the channel,in Hertz	600	real
PhaseJitterFrequencyHz	frequency of phase jitter distortion to add the signal,in Hertz	60	real
LinearDistortionTaps	taps value of FIR filter	(1.0, 0.0)	complex array

Pin Inputs

Pin	Name	Description	Signal Type
1	input		complex

Pin Outputs

Pin	Name	Description	Signal Type
2	output	input signal plus directions	complex

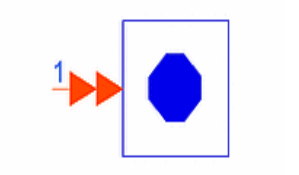
Notes/Equations

1. TkBasebandEquivChannel is a subnetwork; it models a baseband equivalent channel with linear distortion, frequency offset, phase jitter, and additive white Gaussian noise. Many of the channel model parameters can be set dynamically by the user.
2. To model linear distortion, such as intersymbol interference, the input signal is passed through a complex FIR filter with the taps set by LinearDistortionTaps.

The frequency offset distortion is set by the Freq. Offset slider control. Similarly, the phase jitter amplitude (peak-to-peak, in degrees) is set by the Phase Jitter slider control while the phase jitter frequency is set by the PhaseJitterFrequencyHz parameter. The phase of both the frequency offset and the phase jitter can be reset with the Reset Phase control button. The amplitude of the added complex white Gaussian noise is set by the Noise Power slider control.

3. See Also: FIR, FreqPhase, AWGN_Channel, TeleChannel.

TkBreakPt



Description Conditional Breakpoint
Library Interactive Controls and Displays
Class SDFTkBreakPt
Derived From TclScript
C++ Code

Parameters

Name	Description	Default	Type
Condition	condition on which to pause the run	$input(1) < 0	string
OptionalAlternateScript	script to run instead of default		filename

Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to feed to Tcl	multiple anytype

Notes/Equations

1. TkBreakPt evaluates a Tcl expression each time it is simulated. If the expression returns a value of true then the run is paused. The expression can be any valid tcl expression. For details of valid Tcl expressions, refer to the documentation for the Tcl command expr.

   TkBreakPt takes multiple inputs. To easily write a conditional expression, the inputs are numbered: input(1), input(2), input(3), and so on. Therefore, if only one input is connected to a TkBreakPt, use input(1) to refer to it.

   Because Tcl uses a dollar sign ($) to reference the value of a variable, the expression

```
$input(1) < 0
```

will be true if the value of the first input is negative. Similarly, the expression

```
$input(1) < $input(2)
```

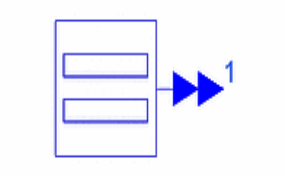
will be true whenever the value of the first input is less than the value of the second input.

It may be difficult to distinguish the inputs if they are all connected directly to the multiport input. One solution is to use the BusMerge component. Connect the bus merge icon of your choice to the input of TkBreakPt. Then connect the inputs to the bus merge icon. The top input is input(1), the next is input(2), and so on.

The OptionalAlternateScript parameter is the script to source if the condition is true. If this parameter is blank then the default script is executed, which pauses the run and displays a message in the Control panel. This should be fine for most applications of TkBreakPt.

2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkButtons



Description **Interactive Buttons**
Library **Interactive Controls and Displays**
Class **SDFTkButtons**
Derived From **TclScript**
C++ Code

Parameters

Name	Description	Default	Type
Label	buttons label	Buttons you can push:	string
Identifiers	list of strings that identify each button; use a space between strings to create multiple buttons	BUTTON1	string array
Value	value produced when a button is pushed	1.0	real
SimultaneousEvents	produce simultaneous output values: do not allow, allow	do not allow	enum
ButtonControl	return to simulation when button is pushed: Not synchronous, Synchronous	Not synchronous	enum
PutInControlPanel	put slide in control panel (versus its own window): NO, YES	YES	enum
OutputType	Pushes produce impulses or levels: Impulse, Level	Impulse	enum

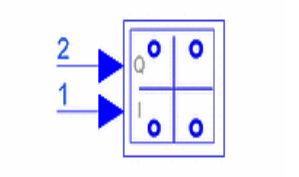
Pin Outputs

Pin	Name	Description	Signal Type
1	output	Any outputs obtained from Tcl	multiple real

Notes/Equations

1. TkButtons outputs 0.0 value on all outputs unless the corresponding button is pushed. When the button is pushed, the output takes the value given by the parameter Value. If ButtonControl is Synchronous, outputs are produced only when some button is pushed—the component waits for a button to be pushed before simulation proceeds. If SimultaneousEvents is allow, button pushes are registered only when PUSH TO PRODUCE OUTPUTS is pushed. (If synchronous is no, TkButtons is nondeterminate.)
2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkConstellation



Description **Tk IQ Constellation**
Library **Interactive Controls and Displays**

Parameters

Name	Description	Default	Type
Label	Plot title	Tk Constellation	string
NumSamplesPerSymbol	Number of samples per symbol	10	int
Amplitude	Y-axis amplitude	2	real
SampleDelay	Input delay before sampling	2	int
Persistence	Number of points displayed on the plot at any one time	200	int
UpdateSize	Number of new points plotted per plot update	10	int
Style	Plot style: dot, connect	connect	enum

Pin Inputs

Pin	Name	Description	Signal Type
1	X	X input	real
2	Y	Y input	real

Notes/Equations

1. The TkConstellation subcircuit displays an IQ constellation of your data. Set NumSamplesPerSymbol to the number of samples per symbol. The X and Y axes of the graph are drawn from +Amplitude to –Amplitude.
2. By setting the Style parameter to connect, your constellation will show the trajectories; setting it to dot will display the constellation as dots. Dot style constellations must be sampled at the appropriate delay. When you simulate, a

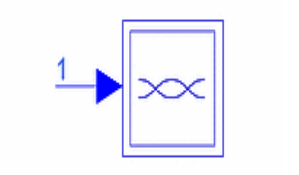
TkSlider component will appear to control this delay. Once you determine a good sampling delay, set the SampleDelay parameter to remember it.

3. The Persistence parameter controls how many points are displayed on the constellation plot at any one time. Only the most recent Persistent number of points are plotted.
4. The UpdateSize parameter controls the number of points drawn on the plot per plot update.

   The update occurs as described next.

   If the total number of samples read (for each input) is less than Persistence, then the most recent UpdateSize samples from each input are used to draw new points in the plot. The first time the total number of samples read exceeds Persistence, for example by N ($1 \leq N \leq$ UpdateSize), the oldest N points are deleted before the new UpdateSize points are drawn, so that the total number of points displayed is equal to Persistence. After this point, every time UpdateSize new samples are read (from each of the two inputs), the oldest UpdateSize points are deleted from the plot and the most recent UpdateSize samples read are used to draw new points in the plot.
5. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkEye



Description **Tk Eye**
Library **Interactive Controls and Displays**

Parameters

Name	Description	Default	Type
Label	Plot title	Tk Eye	string
NumSamplesPerSymbol	Number of samples per symbol	10	real
NumSymbols	Number of symbols on X axis	2	real
Amplitude	Y axis amplitude	2	real
Persistence	Number of points displayed on the plot at any one time	200	real
UpdateSize	Number of new points plotted per plot update	10	real
Style	Plot style: dot, connect	connect	enum

Pin Inputs

Pin	Name	Description	Signal Type
1	X	input signal	real

Notes/Equations

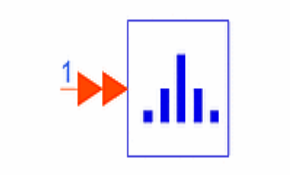
1. The TkEye subcircuit displays an eye diagram of your data. Set NumSamplesPerSymbol to the number of samples per symbol, and NumSymbols to the number of symbols, or eyes, in the resultant diagram. The Y axis of the graph is drawn from +Amplitude to –Amplitude.
2. When you simulate, a TkSlider component will appear to add a variable sample delay to the eye diagram. Using the slider, you can center the eye on your graph.

3. The Persistence parameter controls how many points are displayed on the eye diagram plot at any one time. Only the most recent Persistent number of points are plotted. Using a higher Persistence will result in more signal traces being overlaid on top of each other, which will give a more accurate eye diagram.
4. The UpdateSize parameter controls the number of points drawn on the plot per plot update.

   The update happens as described next.

   If the total number of samples read is less than Persistence, then the most recent UpdateSize samples are used to draw new points in the plot. The first time the total number of samples read exceeds Persistence, for example by N ($1 \leq N \leq$ UpdateSize), the oldest N points are deleted before the new UpdateSize points are drawn, so that the total number of points displayed is equal to Persistence. After this point, every time UpdateSize new samples are read, the oldest UpdateSize points are deleted from the plot and the most recent UpdateSize samples read are used to draw new points in the plot.
5. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkHistogram



Description **Display histogram of inputs**
Library **Interactive Controls and Displays**
Class **SDFTkHistogram**
Derived From **TkBarGraph**
C++ Code

Parameters

Name	Description	Default	Type	Range
Label	Histogram title	Histogram Display	string	
Top	X-axis upper limit	1.0	real	
Bottom	X-axis lower limit	-1.0	real	
NumberOfBars	Number of buckets	16	int	
BarGraphHeight	Bar graph height, in centimeters	5	real	
BarGraphWidth	Bar graph width, in centimeters	10	real	
Position	Bar graph window position offset from upper left corner, in pixels	+0+0	string	
UpdateSize	Number of input samples read per graph update	1	int	
DataPoints	Number of data points to analyze, 0 for all	100	int	[0, ∞)

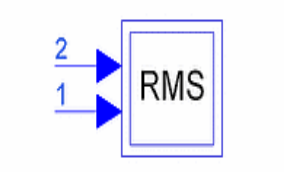
Pin Inputs

Pin	Name	Description	Signal Type
1	input	Inputs to make histograms of	multiple anytype

Notes/Equations/

1. TkHistogram dynamically displays histograms of any number of inputs. NumberOfBars controls the number of bars; Top and Bottom control the ends of the histogram display. Data values less than Bottom and greater than Top are not plotted.
2. TkHistogram will gather statistics on the last DataPoints values as if it were a sliding histogram. When DataPoints is set to 0, the model will gather statistics on all data.
3. The UpdateSize parameter controls how often to update the histogram. Setting it to a higher value will make the model run faster, but histogram updates won't be as smooth.
4. For general information regarding the control and display of simulation data, refer to the "Introduction" on page 1-1.

TkIQrms



Description **Display RMS Value of Input IQ Signal**
Library **Interactive Controls and Displays**

Parameters

Name	Description	Default	Type
Label	label to put on the display	input signal rms value	string

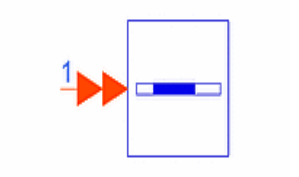
Pin Inputs

Pin	Name	Description	Signal Type
1	I_in	I phase input	real
2	Q_in	Q phase input	real

Notes/Equations

1. This component displays the rms value of the IQ signal connected at its input. The value displayed is the rms value over the period starting at sample 0 and ending at the current sample.
2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkMeter



Description **Bar Meters Display**
Library **Interactive Controls and Displays**
Class **SDFTkMeter**
Derived From **TclScript**
C++ Code

Parameters

Name	Description	Default	Type	Range
Label	display label	sliding scale display	string	
Low	low end of scale for displayed bars	-1.0	string	(-∞, ∞)
High	high end of scale	1.0	string	(Low, ∞)
PutInControlPanel	put bars in control panel (versus their own window): NO, YES	YES	enum	

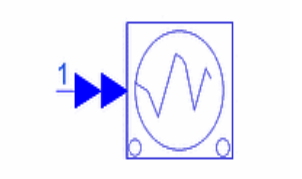
Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to feed to Tcl	multiple anytype

Notes/Equations

1. TkMeter dynamically displays the value of any number of input signals on a set of bar meters.
2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkPlot



Description **Plot Inputs versus Time**
Library **Interactive Controls and Displays**
Class **SDFTkPlot**
Derived From **TkXYPlot**
C++ Code

Parameters

Name	Description	Default	Type
Label	Plot title		string
Geometry	Window size and location (width x height + horizontal offset + vertical offset), in pixels	720x400+0+0	string
xTitle	X-axis label	n	string
yTitle	Y-axis label	y	string
xRange	X-axis values range	0 100	real array
yRange	Y-axis values range	-1.5 1.5	real array
Persistence	Number of points displayed on the plot at any one time	100	int
Style	Plot style: dot, connect	connect	enum
UpdateSize	Number of new points plotted per plot update	10	int
RepeatBorderPoints	Repeat rightmost border point on left border: NO, YES	YES	enum

Pin Inputs

Pin	Name	Description	Signal Type
1	Y	Vertical coordinate	multiple real

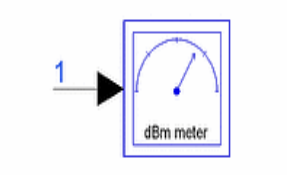
Notes/Equations

1. Plot Y input(s) versus sample number with dynamic updating. Two styles are available: dot causes individual points to be plotted; connect causes connected lines to be plotted. Drawing a box in the plot will reset the plot area to that outlined by the box. Buttons allow for zooming in and out, and for resizing the box to just fit the data in view.
2. The Persistence parameter controls how many points are displayed on the plot at any one time. Only the most recent Persistent number of points are plotted.
3. The UpdateSize parameter controls the number of points drawn on the plot per plot update.

   The update occurs as described next.

   If the total number of samples read is less than Persistence, then the most recent UpdateSize samples are used to draw new points in the plot. The first time the total number of samples read exceeds Persistence, for example by N ($1 \leq N \leq$ UpdateSize), the oldest N points are deleted before the new UpdateSize points are drawn, so that the total number of points displayed is equal to Persistence. After this point, every time UpdateSize new samples are read, the oldest UpdateSize points are deleted from the plot and the most recent UpdateSize samples read are used to draw new points in the plot.
4. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkPower



Description **Display Signal Power in dBm**
Library **Interactive Controls and Displays**

Parameters

Name	Description	Default	Unit	Type	Range
Label	label to put on the display	Power in dBm		string	
SignalType	input signal type: Baseband, RF	RF		enum	
RefR	reference resistance	50	Ohm	real	(0, ∞)
StartUpDelay	number of initial input samples to be ignored	0		int	[0, ∞)
IntegrationSamples	period in number of samples for integrator reset signal (0 never resets the integrator)	0		int	[0, ∞)

Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	timed

Notes/Equations

1. This component accepts a timed signal at its input and displays its average power in dBm.
   - If IntegrationSamples=0, then the value displayed is the average power over the time period starting at time zero and ending at the current time.
   - If IntegrationSamples>0, then the integrator used to calculate the average power is reset periodically every IntegrationSamples samples.

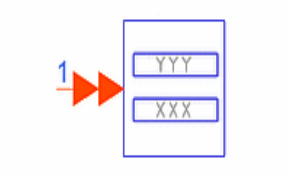
If the resulting average power value is less than -300 dBm, TkPower will display -300 dBm as the average power.

2. The StartUpDelay parameter can be used to exclude an initial number of input samples from the average power calculation. This can be useful when trying to exclude transients or other initial signal delays. For the initial period of StartUpDelay samples the value displayed by TkPower is -300 dBm.
3. If RefR < 0 or = 0, it is reset to 50 Ohms.

   If StartUpDelay < 0, it is reset to 0.

   If IntegrationSamples < 0, it is reset to 0.
4. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkShowBooleans



Description **Booleans Display**
Library **Interactive Controls and Displays**
Class **SDFTkShowBooleans**
Derived From **TclScript**
C++ Code

Parameters

Name	Description	Default	Type
Label	title for set of Boolean displays	Inputs to TkShowBooleans:	string
Identifiers	identifier for each input for display	BOOL	string array
PutInControlPanel	put bars in control panel (versus their own window): NO, YES	YES	enum

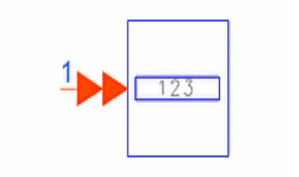
Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to feed to Tcl	multiple anytype

Notes/Equations

1. TkShowBooleans displays input Booleans using color to highlight their value.
2. Zero is false; non-zero is true.
3. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkShowValues



Description Input Values Display
Library Interactive Controls and Displays
Class SDFTkShowValues
Derived From TclScript
C++ Code

Parameters

Name	Description	Default	Type
Label	display label	Inputs to TkShowValues:	string
PutInControlPanel	put bars in control panel (versus their own window): NO, YES	YES	enum

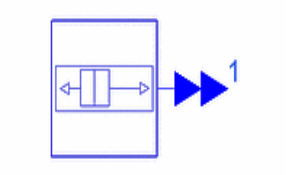
Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to feed to Tcl	multiple anytype

Notes/Equations

1. TkShowValues displays the input values in textual form. The print() method of the input particles is used, so any data type can be handled, although the space allocated on the screen may need to be adjusted. The width of the display window is appropriate for integer, floating-point (real), and complex particles.
2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkSlider



Description Interactive Slider
Library Interactive Controls and Displays
Class SDFTkSlider
Derived From TclScript
C++ Code

Parameters

Name	Description	Default	Type
Low	low end of interactive scale	0.0	real
High	high end of interactive scale	1.0	real
Value	initial value to send to output	0.0	real
Identifier	identifier for control panel slider	Scale	string
PutInControlPanel	put bars in control panel (versus their own window): NO, YES	YES	enum
Granularity	number of intervals in slider	100	int

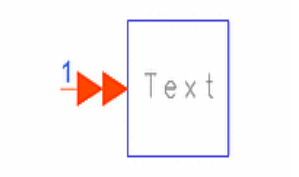
Pin Outputs

Pin	Name	Description	Signal Type
1	output	Any outputs obtained from Tcl	multiple real

Notes/Equations

1. TkSlider outputs a value determined by an interactive on-screen scale slider.
2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkText



Description **Display History of Input Values**
Library **Interactive Controls and Displays**
Class **SDFTkText**
Derived From **TkShowValues**
C++ Code

Parameters

Name	Description	Default	Type
Label	display label	Inputs to TkText:	string
NumberOfPastValues	number of past values to save	100	int

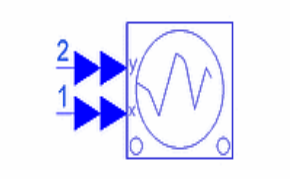
Pin Inputs

Pin	Name	Description	Signal Type
1	input	Any number of inputs to feed to Tcl	multiple anytype

Notes/Equations

1. TkText will display input values in a separate window and keep a specified number of past values. The print() method of the input particles is used, so any data type can be handled. The default width of the display window is appropriate for integer, floating-point (real), and complex particles.
2. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

TkXYPlot



Description **Plot Y versus X Inputs**
Library **Interactive Controls and Displays**
Class **SDFTkXYPlot**
C++ Code

Parameters

Name	Description	Default	Type
Label	Plot title		string
Geometry	Window size and location (width x height + horizontal offset + vertical offset), in pixels	720x400+0+0	string
xTitle	X-axis label	x	string
yTitle	Y-axis label	y	string
xRange	X-axis values range	-1.5 1.5	real array
yRange	Y-axis values range	-1.5 1.5	real array
Persistence	Number of points displayed on the plot at any one time	100	int
Style	Plot style: dot, connect	dot	enum
UpdateSize	Number of new points plotted per plot update	10	int

Pin Inputs

Pin	Name	Description	Signal Type
1	X	Horizontal coordinate	multiple real
2	Y	Vertical coordinate	multiple real

Notes/Equations

1. Plot Y input(s) versus X input(s) with dynamic updating. Two styles are available: dot causes points to be plotted; connect causes connected lines to be plotted. Drawing a box in the plot will reset the plot area to that outlined by the box. Buttons allow for zooming in and out, and for resizing the box to just fit the data in view.
2. The Persistence parameter controls how many points are displayed on the plot at any one time. Only the most recent Persistent number of points are plotted.
3. The UpdateSize parameter controls the number of points drawn on a plot per plot update.

   The update occurs as described next.

   If the total number of samples read (for each input) is less than Persistence, then the most recent UpdateSize samples from each input are used to draw new points in the plot. The first time the total number of samples read exceeds Persistence, for example by N ($1 \leq N \leq$ UpdateSize), the oldest N points are deleted before the new UpdateSize points are drawn, so that the total number of points displayed is equal to Persistence. After this point, every time UpdateSize new samples are read (from each of the two inputs), the oldest UpdateSize points are deleted from the plot and the most recent UpdateSize samples read are used to draw new points in the plot.
4. For general information regarding the control and display of simulation data, refer to the “Introduction” on page 1-1.

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